

Concepts and applications of multi-directional finite difference method

—
in memory of Prof. Kunio Kuwahara

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Professor Kuwahara developed multi-directional finite difference method around 1990. Previously, he had long been considering some possibilities of construction of a more natural finite difference method. Finally, he arrived at a new strategy, which was simple but which had nevertheless been difficult to strike upon:

- i. If one has a finite difference mesh as presented in Fig. 1.
- ii. Another mesh system can be considered by $\pi/4$ rotation, as shown in Fig. 2.
- iii. The results from both mesh systems can be mixed in appropriate weights

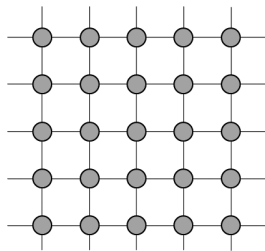


Fig. 1 Original mesh

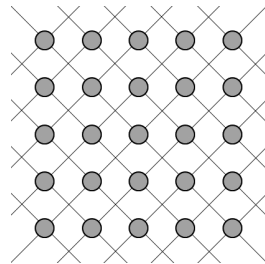


Fig. 2 Rotated mesh

The weights of both mesh systems were determined to render the leading term of the truncation error as invariant for rotation. If one had a CFD code for a generalized coordinate system, then necessary code modifications would be straightforward, the increase of computational time would be minimal and the flow computation stability increases greatly.

After establishing the multi-directional finite difference method, Prof. Kuwahara utilized it for various applications and various new techniques—such as the multi-grid approach—in quite an exciting manner, as we all know.

References

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